

# On the Fixed Charge Transportation Problem

Roberto Roberti

DEI - University of Bologna

Joint work with Aristide Mingozzi (Dept. of Mathematics - University of Bologna)

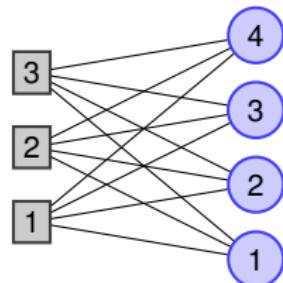
ROUTE 2014 - June 1st, 2014

# The Fixed Charge Transportation Problem (FCTP)

- $S = \{1, 2, \dots, m\}$  set of  $m$  origins
- $T = \{1, 2, \dots, n\}$  set of  $n$  destinations
- $a_i \in \mathbb{N}$  supply at  $i \in S$
- $b_j \in \mathbb{N}$  demand of  $j \in T$
- $c_{ij}$  unit cost for shipping from  $i \in S$  to  $j \in T$
- $f_{ij}$  fixed cost for serving  $j \in T$  from  $i \in S$
- Assumption, w.l.o.g.,  $\sum_{i \in S} a_i = \sum_{j \in T} b_j$

Bipartite graph  
 $G = (S, T, E)$ , where  
 $E = \{(i, j) : i \in S, j \in T\}$

Origins      Destinations



## Objective

Minimize the total fixed and variable cost for serving all destinations

## Basic Formulation of the FCTP

- $x_{ij} \in \mathbb{R}_+$  flow along  $\{i,j\} \in E$
- $y_{ij} \in \{0,1\}$  use of  $\{i,j\} \in E$
- $m_{ij} = \min \{a_i, b_j\}$ ,  $\{i,j\} \in E$

$$(F0) \quad \min \sum_{\{i,j\} \in E} (c_{ij}x_{ij} + f_{ij}y_{ij}) \quad (1)$$

$$\text{s.t. } \sum_{j \in T} x_{ij} = a_i \quad i \in S \quad (2)$$

$$\sum_{i \in S} x_{ij} = b_j \quad j \in T \quad (3)$$

$$0 \leq x_{ij} \leq m_{ij}y_{ij} \quad \{i,j\} \in E \quad (4)$$

$$y_{ij} \in \{0,1\} \quad \{i,j\} \in E \quad (5)$$

- LF0 linear relaxation of F0 ( $z(\text{LF0})$  its optimal solution cost)

### Observation

Any optimal FCTP solution is a *basic feasible solution* of (2)-(3)

# Literature Review on Exact Algorithms

- Branch-and-bound
  - Kennington and Unger, *Management Science* (1976)
  - Barr, Glover and Krigman, *Operations Research* (1981)
  - Cabot and Erenguc, *Naval Research Logistics Quarterly* (1984)
  - Cabot and Erenguc, *Management Science* (1986)
  - Palekar, Karwan and Zionts, *Management Science* (1990)
  - Lamar and Wallace, *Management Science* (1997)
- Branch-and-cut
  - Agarwal and Aneja, *Operations Research* (2012)
- Branch-and-cut-and-price
  - Roberi, Bartolini and Mingozi, *Management Science* (2014) - forthcoming

## Real-Life Applications of the FCTP

- Allocation of launch vehicles to space missions: Stroup, *Operations Research* (1967)
- Process selection: Hirsch and Dantzig, *Naval Research Logistics Quarterly* (1968)
- Solid-waste management: Walker, *Management Science* (1976)
- Teacher assignment: Hultberg and Cardoso, *European Journal of Operational Research* (1997)
- Distribution and transportation systems: Adlakha and Kowalski, *Omega* (2003)

# Single-Pattern Formulation

Roberti, Bartolini and Mingozi (2014)

An origin pattern of  $i \in S$  is a vector  $\mathbf{w} \in \mathbb{Z}_+^n$  s.t.

$$w_1 + w_2 + \dots + w_n = a_i$$

and

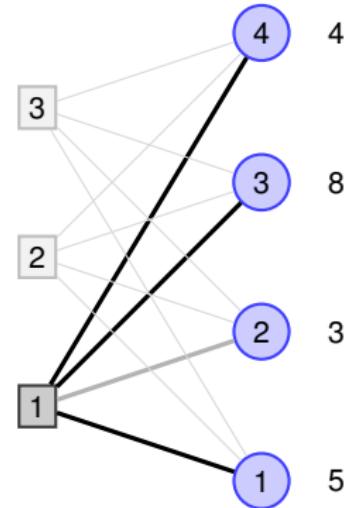
$$0 \leq w_j \leq m_{ij} \quad j \in T$$

$W_i$ : index set of all origin patterns of  $i \in S$

$W$ : set of all origin patterns ( $W = \bigcup_{i \in S} W_i$ )

$d_\ell$ : cost of origin pattern  $\ell \in W_i$

$$d_\ell = \sum_{j \in T : w_j^\ell > 0} (c_{ij} w_j^\ell + f_{ij})$$



$$\mathbf{w} = [5 \ 0 \ 1 \ 4]$$

$$d_\ell = f_{11} + 5c_{11} + f_{13} + c_{13} + f_{14} + 4c_{14}$$

## Single-Pattern Formulation

### Formulation

$\xi_\ell \in \{0, 1\}$  for origin pattern  $\ell \in W$

$$(F1) \quad \min \sum_{\ell \in W} d_\ell \xi_\ell \quad (6)$$

$$\text{s.t. } \sum_{\ell \in W} w_j^\ell \xi_\ell = b_j \quad j \in T \quad (7)$$

$$\sum_{\ell \in W_i} \xi_\ell = 1 \quad i \in S \quad (8)$$

$$\xi_\ell \in \{0, 1\} \quad \ell \in W \quad (9)$$

LF1 linear relaxation of F1 ( $z(\text{LF1})$  its optimal solution cost)

- $v_j$  dual variable of constraint (7) for  $j \in T$
- $u_i$  dual variable of constraint (8) for  $i \in S$

Proposition

$$z(\text{LF1}) \geq z(\text{LF0})$$

## Single-Pattern Formulation

### Pricing Problem

For each  $i \in S$ , the pricing problem  $PR_i$  is a Multiple Choice Knapsack

- For each  $j \in T$  and each flow  $q = 1, \dots, m_{ij}$ , let  $\varphi_{jq} \in \{0, 1\}$

$$\begin{aligned} (PR_i) \quad & \min \quad \sum_{j \in T} \sum_{q=1}^{m_{ij}} (f_{jq} + q(c_{ij} - v_j)) \varphi_{jq} - u_i \\ \text{s.t.} \quad & \sum_{j \in T} \sum_{q=1}^{m_{ij}} q \varphi_{jq} = a_i \\ & \sum_{q=1}^{m_{ij}} \varphi_{jq} \leq 1 \quad j \in T \\ & \varphi_{jq} \in \{0, 1\} \quad j \in T \quad q = 1, \dots, m_{ij} \end{aligned}$$

- $PR_i$  can be solved by dynamic programming recursions

## Single-Pattern Formulation

### Reversing Origins and Destinations

- The FCTP is symmetric in the origins and destinations
- Lower bound  $z(LF1)$  can also be computed by reversing origins and destinations
- Hereafter, we assume that origins and destinations are reversed if this provides a better lower bound  $z(LF1)$

# Single-Pattern Formulation

## Valid Inequalities

Lower bound  $z(\underline{\text{LF1}})$  can be tightened with the following cuts

- Set Covering: Agarwal and Aneja (2012)
- Chvátal-Gomory: Gomory (1958), Chvátal (1973)
- Lifted Chvátal-Gomory NEW
- Extended Generalized Upper Bound Cover: Gu et al. (1998)
- Feasibility NEW
- Couple NEW

Only robust cuts are considered

- $\underline{\text{LF1}}$  problem  $\text{LF1}$  plus all valid inequalities mentioned ( $z(\underline{\text{LF1}})$  its optimal solution cost)

# Single-Pattern Formulation

Outline of the Exact Algorithm of Roberti et al. (2014)

- Computes lower bound  $z(\overline{LF1})$  at the root node
- Cuts separated at the root node only
- Branching on edges  $\{i,j\} \in E$
- Nodes explored with best-bound strategy

# Double-Pattern Formulation

## Introduction

A destination pattern of  $j \in T$  is a vector  $\bar{w} \in \mathbb{Z}_+^m$  s.t.

$$\bar{w}_1 + \bar{w}_2 + \dots + \bar{w}_m = b_j$$

and

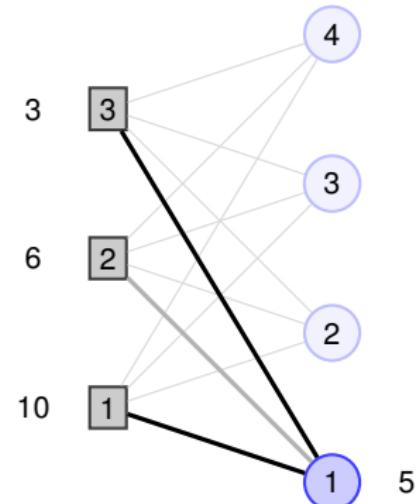
$$0 \leq \bar{w}_i \leq m_{ij} \quad i \in S$$

$\bar{W}_j$ : index set of all destination patterns of  $j \in T$

$\bar{W}$ : set of all destination patterns ( $\bar{W} = \bigcup_{j \in T} \bar{W}_j$ )

$\bar{d}_\ell$ : cost of destination pattern  $\ell \in \bar{W}_j$

$$\bar{d}_\ell = \sum_{i \in S : \bar{w}_i^\ell > 0} (c_{ij} \bar{w}_i^\ell + f_{ij})$$



$$\bar{w} = [2 \ 0 \ 3]$$

$$\bar{d}_\ell = f_{11} + 2c_{11} + f_{31} + 3c_{31}$$

## Double-Pattern Formulation

### Formulation

$\xi_\ell \in \{0, 1\}$  for  $\ell \in W$ , and  $\bar{\xi}_\ell \in \{0, 1\}$  for  $\ell \in \bar{W}$

$$\begin{aligned} (\text{F2}) \quad & \min \quad \frac{1}{2} \sum_{\ell \in W} d_\ell \xi_\ell + \sum_{\ell \in \bar{W}} \bar{d}_\ell \bar{\xi}_\ell \\ \text{s.t.} \quad & \sum_{\ell \in W_i} \xi_\ell = 1 \quad i \in S \\ & \sum_{\ell \in \bar{W}_j} \bar{\xi}_\ell = 1 \quad j \in T \\ & \sum_{\ell \in W_i} w_j^\ell \xi_\ell = \sum_{\ell \in \bar{W}_j} \bar{w}_i^\ell \bar{\xi}_\ell \quad \{i, j\} \in E \\ & \sum_{\ell \in W} d_\ell \xi_\ell = \sum_{\ell \in \bar{W}} \bar{d}_\ell \bar{\xi}_\ell \\ & \xi_\ell \in \{0, 1\} \quad \ell \in W \quad \bar{\xi}_\ell \in \{0, 1\} \quad \ell \in \bar{W} \end{aligned}$$

LF2 linear relaxation of F2 ( $z(\text{LF2})$  its optimal solution cost)

Proposition

$$z(\text{LF2}) \geq z(\text{LF1}) \geq z(\text{LF0})$$

## Double-Pattern Formulation

Valid Inequalities and Comparison with the Single-Pattern Formulation

$z(\text{LF2})$  can be tightened with the following Edge-Quantity (EQ) equalities

$$\sum_{\ell \in W_i : w_j^\ell = q} \xi_\ell = \sum_{\ell \in \bar{W}_j : \bar{w}_i^\ell = q} \bar{\xi}_\ell \quad \{i, j\} \in E \quad q = 1, \dots, m_{ij}$$

- $\overline{\text{LF2}}$  problem  $\text{LF2}$  plus EQs ( $z(\overline{\text{LF2}})$  its optimal solution cost)
- Problem  $\overline{\text{LF2}}$  implies the following cuts derived for  $\text{F1}$ 
  - Chvátal-Gomory
  - Lifted Chvátal-Gomory
  - Extended Generalized Upper Bound Cover
  - Feasibility
  - Couple

### Proposition

$z(\overline{\text{LF2}}) \geq (z(\overline{\text{LF1}}) \text{ without Set Covering inequalities})$

# Double-Pattern Formulation

Outline of the New Exact Branch-and-Cut-and-Price Algorithm

- Lower bound at the root node given by  $z(\overline{\text{LF2}})$ 
  - EQs separated by inspection
  - Pricing problem solved with dynamic programming recursions
- Cuts are separated at each node of the search tree
- Branching on edges  $\{i,j\} \in E$
- Nodes explored with best-bound strategy

# Computational Results

## Test Instances

- 390 instances
  - 30 proposed by Agarwal and Aneja (2012): 3 classes of 10 instances each
  - 180 proposed by Roberti et al. (2014): 18 classes of 10 instances each
  - 180 new instances: 18 classes of 10 instances each
- All 390 instances feature
  - $m = n$
  - $f_{ij}$  random in [200, 800]
  - Variable costs that amount for  $\theta\%$  of the total cost, with  $\theta = 0, 20, 50$
  - $a_i$  and  $b_j$  random in the range [1,  $B$ ], with  $B = 20, 50, 100$

# Computational Results

Instances proposed by Agarwal and Aneja (2012)

$n = 15$  and  $B = 20$

$\theta$	Cplex 12.5				AA12				Single-Pattern				Double-Pattern				
	LF0	$\overline{LF0}$	Opt	T	LBr	Opt	T	LF1	$\overline{LF1}$	Nds	Opt	T	LF2	$\overline{LF2}$	Nds	Opt	T
0	74.9	91.5	10	20	89.6	10	139	84.0	99.5	9	10	0.8	88.8	99.9	1	10	0.2
20	81.9	95.3	10	36	92.5	8	51	88.2	99.6	11	10	0.5	92.9	99.9	1	10	0.2
50	85.7	96.4	10	18	93.6	9	61	92.3	99.7	12	10	0.6	94.0	99.8	2	10	0.2
	<b>80.8</b>	<b>94.4</b>	<b>30</b>	<b>25</b>	<b>91.9</b>	<b>27</b>	<b>87</b>	<b>88.2</b>	<b>99.6</b>		<b>30</b>	<b>0.6</b>	<b>91.9</b>	<b>99.9</b>		<b>30</b>	<b>0.2</b>

AA12: Agarwal and Aneja (2012) - 600 secs of time limit - Cplex 11.2 - machine  $\approx 2\times$  slower than ours

# Computational Results

Instances proposed by Roberti et al. (2014)

$B = 20$

Cplex 12.5				Single-Pattern				Double-Pattern							
n	$\theta$	LF0	$\overline{LF0}$	Opt	T	LF1	$\overline{LF1}$	Nds	Opt	T	LF2	$\overline{LF2}$	Nds	Opt	T
30	0	81.8	94.2	4	3221	88.5	99.1	234	10	13	93.2	99.4	20	10	2
30	20	84.7	95.0	6	4784	90.4	99.4	176	10	11	93.7	99.5	19	10	2
30	50	87.1	96.2	8	1850	91.9	99.5	90	10	9	94.4	99.6	11	10	2
50	0	82.8	94.7	0	-	89.7	99.3	2110	10	116	94.3	99.5	123	10	24
50	20	85.5	95.0	0	-	90.6	99.4	1109	10	95	94.4	99.6	71	10	18
50	50	88.7	96.3	0	-	93.3	99.5	7489	10	324	95.5	99.7	161	10	39
70	0	85.0	95.3	0	-	90.7	99.5	3251	10	421	95.3	99.6	180	10	76
70	20	86.8	95.6	0	-	91.4	99.5	12830	9	1055	95.5	99.6	429	10	169
70	50	89.6	96.4	0	-	93.3	99.6	14306	10	1395	96.2	99.7	353	10	166
<b>85.8 95.4 18</b>				<b>91.1 99.4</b>				<b>89 375</b>				<b>94.7 99.6</b>			

10800 seconds of time limit

# Computational Results

Instances proposed by Roberti et al. (2014)

$B = 50$

Cplex 12.5				Single-Pattern				Double-Pattern							
n	$\theta$	LF0	$\overline{LF0}$	Opt	T	LF1	$\overline{LF1}$	Nds	Opt	T	LF2	$\overline{LF2}$	Nds	Opt	T
20	0	73.6	89.8	4	4569	83.1	98.1	1306	10	37	87.7	99.1	16	10	4
20	20	79.2	92.8	7	2269	86.2	98.5	444	10	16	90.2	99.4	8	10	2
20	50	84.1	94.9	10	1234	90.0	99.0	282	10	13	92.7	99.7	4	10	2
30	0	76.6	90.4	0	-	83.8	98.3	5497	10	353	89.1	99.1	44	10	16
30	20	78.0	90.6	0	-	85.0	98.3	11264	10	899	89.2	99.2	49	10	22
30	50	83.9	93.6	0	-	89.0	98.7	5676	10	387	91.9	99.5	34	10	13
40	0	77.6	90.4	0	-	84.3	98.0	51214	5	5060	89.9	99.0	269	10	153
40	20	80.4	92.0	0	-	87.2	98.4	18443	6	1793	91.1	99.1	434	10	265
40	50	84.8	93.6	0	-	89.8	98.7	13870	3	1741	92.5	99.3	216	10	125
<b>79.8</b> <b>92.0</b> <b>21</b>				<b>86.5</b> <b>98.4</b>				<b>74</b> <b>788</b>				<b>90.5</b> <b>99.3</b>			
10800 seconds of time limit															

# (Preliminary) Computational Results

## New Instances

B = 20

		Double-Pattern				
n	$\theta$	LF2	Nds	Opt	T	
100	0	99.6	1289	10	925	
100	20	99.7	1765	10	1721	
100	50	99.7	1614	10	1840	
120	0	99.7	4115	10	5156	
120	20	99.7	4159	9	4581	
120	50	99.7	5058	10	9679	

B = 50

		Double-Pattern				
n	$\theta$	LF2	Nds	Opt	T	
50	0	99.1	1579	10	1191	
50	20	99.3	656	10	503	
50	50	99.4	351	10	340	
60	0	99.2	2583	10	3960	
60	20	99.3	2081	10	4180	
60	50	99.4	1181	10	1771	

B = 100

		Double-Pattern				
n	$\theta$	LF2	Nds	Opt	T	
40	0	98.7	962	10	1981	
40	20	99.0	424	10	726	
40	50	99.5	123	10	197	
50	0	98.8	3319	10	12617	
50	20	99.1	2378	10	6956	
50	50	99.2	891	10	2765	

# Bibliography I

- [Adlakha and Kowalski 2003] V. Adlakha and K. Kowalski  
A simple heuristic for solving small Fixed-Charge Transportation Problems  
*Omega* 31(3) 205-211. 2003
- [Agarwal and Aneja 2012] Y. Agarwal and Y. Aneja  
Fixed-charge transportation problem: Facets of the projection polyhedron  
*Operations Research* 60(3) 638-654. 2012
- [Barr et al. 1981] R. S. Barr, F. Glover, and D. Klingman  
A new optimization method for large scale fixed charge transportation problems  
*Operations Research* 29(3) 448-463. 1981
- [Cabot and Erenguc 1984] A. V. Cabot and S. S. Erenguc  
Some branch and bound procedures for fixed cost transportation problems  
*Naval Research Logistics Quarterly* 31(1) 145-154. 1984
- [Cabot and Erenguc 1986] A. V. Cabot and S. S. Erenguc  
Improved penalties for fixed cost linear programs using lagrangean relaxation  
*Management Science* 32(1) 856-869. 1986
- [Chvátal 1973] V. Chvátal  
Edmonds polytopes and a hierarchy of combinatorial problems  
*Discrete Mathematics* 4(4) 305-337. 1973

## Bibliography II

[Gomory 1958] R. E. Gomory

Outline of an algorithm for integer solutions to linear programs  
Bulletin of the AMS 4 275-278. 1958

[Gu et al. 1998] Z. Gu, G. L. Nemhauser, and M. W. P. Savelsbergh  
Lifted cover inequalities for 0-1 integer programs: Computation  
INFORMS Journal on Computing 10(4) 427-437. 1998

[Hirsch and Dantzig 1968] W. M. Hirsch and G. B. Dantzig  
The Fixed Charge Problem  
Naval Research Logistics Quarterly 15 413-424. 1968

[Hultberg and Cardoso 1997] T. H. Hultberg and D. M. Cardoso  
The Teacher Assignment Problem: A special case of the Fixed Charge Transportation Problem  
European Journal of Operational Research 101(3) 463-473. 1997

[Kennington and Unger 1976] J. Kennington and E. Unger  
A new branch-and-bound algorithm for the fixed-charge transportation problem  
Management Science 22(10) 1116-1126. 1976

[Lamar and Wallace 1997] B. W. Lamar and C. A. Wallace  
Revised-modified penalties for fixed charge transportation problems  
Management Science 43(10) 1431-1436. 1997

## Bibliography III

[Palekar et al. 1990] U. S. Palekar, M. H. Karwan, and S. Zions

A branch and bound method for the fixed charge transportation problem  
Management Science 36(9) 1092-1105. 1990

[Roberti et al. 2014] R. Roberti, E. Bartolini, A. Mingozzi.

The Fixed Charge Transportation Problem: An exact algorithm based on a new integer programming formulation  
Management Science (forthcoming). 2014.

[Stroup 1967] J. W. Stroup

Allocation of launch vehicles to space missions: a Fixed-Cost Transportation Problem  
Operations Research 15(6) 1157-1163. 1967

[Walker 1976] W. E. Walker

A heuristic adjacent extreme point algorithm for the fixed charge problem  
Management Science 22(5) 587-596. 1976